

### Section 9: Detection v.s. Recovery <sup>a</sup>

- Sections: Wed, 7:30-8:30pm (SC 705); OHs: Wed 8:30-9:30pm (SC 316.07).
- All the section materials (handouts & solutions) can be found either on Canvas or here.

<sup>a</sup>This handout is based on [9].

**Definition 1.** Let distributions  $P_n, Q_n$  be defined on the measurable space  $(\Omega_n, \mathcal{F}_n)$ . We say that the sequence  $Q_n$  is contiguous to  $P_n$ , and write  $Q_n \triangleleft P_n$ , if for any sequence  $A_n$  of events,

$$\lim_{n \rightarrow \infty} P_n(A_n) = 0 \implies \lim_{n \rightarrow \infty} Q_n(A_n) = 0.$$

**Lemma 1.** If  $Q_n \triangleleft P_n$ , then there is no hypothesis test of the alternative  $Q_n$  against the null  $P_n$  with  $\Pr[\text{type I error}] + \Pr[\text{type II error}] = o(1)$ .

Note that  $Q_n \triangleleft P_n$  and  $P_n \triangleleft Q_n$  are not equivalent, but either of them implies non-distinguishability.

Our goal today is to show thresholds below which spiked and unspiked random matrix models are contiguous.

**Lemma 2.** Let  $\{P_n\}$  and  $\{Q_n\}$  be two sequences of distributions on  $(\Omega_n, \mathcal{F}_n)$ . If the second moment

$$\mathbb{E}_{P_n} \left[ \left( \frac{dQ_n}{dP_n} \right)^2 \right]$$

exists and remains bounded as  $n \rightarrow \infty$ , then  $Q_n \triangleleft P_n$ .

1. Prove this lemma.

**Solution:** Let  $\{A_n\}$  be a sequence of events. Using Cauchy-Schwarz,

$$Q_n(A_n) = \int_{A_n} \frac{dQ_n}{dP_n} dP_n \leq \sqrt{\int_{A_n} \left( \frac{dQ_n}{dP_n} \right)^2 dP_n} \cdot \sqrt{\int_{A_n} dP_n}.$$

The first factor on the right-hand side is bounded; so if  $P_n(A_n) \rightarrow 0$  then also  $Q_n(A_n) \rightarrow 0$

**Solution:** Moreover, given a value of the second moment, we are able to obtain bounds on the tradeoff between type I and type II error in hypothesis testing, which are valid nonasymptotically. Note that this implies, showing that two (sequences of) distributions are contiguous does not rule out the existence of a test that distinguishes between them with constant error probability (better than random guessing).

**Lemma 3.** Consider a hypothesis test of a simple alternative  $Q$  against a simple null  $P$ . Let  $\alpha$  be the probability of type I error, and  $\beta$  the probability of type II error. Regardless of the test, we must have

$$\frac{(1 - \beta)^2}{\alpha} + \frac{\beta^2}{(1 - \alpha)} \leq \mathbb{E}_P \left( \frac{dQ}{dP} \right)^2,$$

assuming the right-hand side is defined and finite. Furthermore, this bound is tight: for any  $\alpha, \beta \in (0, 1)$  there exist  $P, Q$  and a test for which equality holds.

2. Prove the lemma above and discuss the difference between Lemma 2 and Lemma 3.

**Solution:** Let  $A$  be the event that the test selects the alternative  $Q$ , and let  $\bar{A}$  be its complement.

$$\begin{aligned} \mathbb{E}_P \left( \frac{dQ}{dP} \right)^2 &= \int \frac{dQ}{dP} dQ = \int_A \frac{dQ}{dP} dQ + \int_{\bar{A}} \frac{dQ}{dP} dQ \\ &\geq \frac{(\int_A dQ)^2}{\int_A (dP/dQ)dQ} + \frac{(\int_{\bar{A}} dQ)^2}{\int_{\bar{A}} (dP/dQ)dQ} = \frac{(1 - \beta)^2}{\alpha} + \frac{\beta^2}{(1 - \alpha)}, \end{aligned}$$

where the inequality follows from Cauchy-Schwarz. The following example shows tightness: let  $P = \text{Bernoulli}(\alpha)$  and let  $Q = \text{Bernoulli}(1 - \beta)$ . On input 0, the test chooses  $P$ , and on input 1, it chooses  $Q$ .

**Definition 2** (Gaussian Wigner Spiked Matrix Model). We observe  $Y = \lambda xx + \frac{1}{\sqrt{n}}W$ , where  $W$  is an  $n \times n$  random symmetric matrix with entries drawn iid (up to symmetry) from a fixed distribution of mean 0 and variance 1.

**Question 1.** Can we “detect” whether there is a spike or not?

3. Try to formalize the question above. Is there a difference between “detection” and “recovery”?

**Solution:**

We will adopt a Bayesian point of view from now on. Namely, we assume a priori  $x \sim \mathcal{X}$ , where  $\mathcal{X} = \mathcal{X}_n$  is a sequence of distributions on  $\mathbb{R}^n$ , with the default example being  $\mathcal{N}(0, I_n/n)$ . It is understood that  $\|x\| \approx 1$ . We use  $\text{GWig}_n(\lambda, \mathcal{X})$  to denote the corresponding distribution of  $Y$ .

**Lemma 4.** Let  $\lambda \geq 0$ . Let  $Q_n = \text{GWig}_n(\lambda, \mathcal{X})$  and  $P_n = \text{GWig}_n(0)$ . Let  $x$  and  $x'$  be independently drawn from  $\mathcal{X}_n$ . Then

$$\mathbb{E}_{P_n} \left( \frac{dQ_n}{dP_n} \right)^2 = \mathbb{E}_{x, x'} \exp \left( \frac{n\lambda^2}{2} \langle x, x' \rangle^2 \right)$$

4. Prove Lemma 4.

**Solution:** Let  $Q_n = \text{GWig}_n(\lambda, \mathcal{X})$ , i.e., the spiked distribution, and  $P_n = \text{GWig}_n(0)$ , i.e., the unspiked distribution. First, we simplify the likelihood ratio:

$$\begin{aligned} \frac{dQ_n}{dP_n} &= \frac{\mathbb{E}_{x \sim \mathcal{X}_n} \exp\left(-\frac{n}{4} \langle Y - \lambda x x^\top, Y - \lambda x x^\top \rangle\right)}{\exp\left(-\frac{n}{4} \langle Y, Y \rangle\right)} \\ &= \mathbb{E}_{x \sim \mathcal{X}_n} \exp\left(\frac{\lambda n}{2} \langle Y, x x^\top \rangle - \frac{n\lambda^2}{4} \langle x x^\top, x x^\top \rangle\right). \end{aligned}$$

Now passing to the second moment:

$$\begin{aligned} \mathbb{E}_{P_n} \left( \frac{dQ_n}{dP_n} \right)^2 &= \mathbb{E}_{x, x' \sim \mathcal{X}_n} \mathbb{E}_{P_n} \exp\left(\frac{\lambda n}{2} \langle Y, x x^\top + x' x'^\top \rangle \right. \\ &\quad \left. - \frac{n\lambda^2}{4} (\langle x x^\top, x x^\top \rangle + \langle x' x'^\top, x' x'^\top \rangle) \right) \end{aligned}$$

where  $x$  and  $x'$  are drawn independently from  $\mathcal{X}_n$ . We now simplify the Gaussian moment-generating function over the randomness of  $Y$ , and cancel terms, to arrive at the expression

$$= \mathbb{E}_{x, x'} \exp\left(\frac{n\lambda^2}{2} \langle x, x' \rangle^2\right),$$

which proves Lemma 4.

It is well known that our spiked Wigner model admits the following spectral behavior.

**Theorem 1.** *Let  $Y$  be drawn from  $\text{GWig}(\lambda, \mathcal{X})$  with any spike prior  $\mathcal{X}$  supported on unit vectors ( $\|x\| = 1$ ):*

- *If  $\lambda \leq 1$ , the top eigenvalue of  $Y$  converges almost surely to 2 as  $n \rightarrow \infty$ , and the top (unit-norm) eigenvector  $v$  has trivial correlation with the spike:  $\langle v, x \rangle^2 \rightarrow 0$  almost surely.*
- *If  $\lambda > 1$ , the top eigenvalue converges almost surely to  $\lambda + 1/\lambda > 2$ , and  $v$  estimates the spike nontrivially:  $\langle v, x \rangle^2 \rightarrow 1 - 1/\lambda^2$  almost surely.*

5. Prove that for  $\lambda < 1$  “detection” is impossible, assuming  $x_i \stackrel{iid}{\sim} \mathcal{N}(0, 1/n)$ .

**Solution:** Please see [9][Prop. 3.8.]

6. Compare this result to Theorem 1. Do the thresholds for detection and recovery match? What about more general noise distributions and more general priors on  $x$ ?

**Solution:** First of all, roughly speaking, the spectral behavior of this model exhibits universality: regardless of the choice of the noise distributions, many properties of the spectrum behave the same as if the noise came from a standard Gaussian distribution. In particular, for  $\lambda \leq 1$ , the spectrum bulk has a semicircular distribution and the maximum eigenvalue converges almost surely to 2. For  $\lambda > 1$ , an isolated eigenvalue emerges from the bulk with value converging to  $\lambda + 1/\lambda$ , and (under suitable assumptions) the top eigenvector has squared correlation  $1 - 1/\lambda^2$  with the truth. In stark contrast, from a statistical standpoint, universality breaks down entirely: the detection problem becomes easier when the noise is non-Gaussian. Equivalently, the detection threshold is actually lower than 1 in the non-Gaussian case, or in other words, Gaussian noise is the hardest! See [9] for more details.

## References

- [1] BAYATI, M., AND MONTANARI, A. The dynamics of message passing on dense graphs, with applications to compressed sensing. *IEEE Transactions on Information Theory* 57, 2 (2011), 764–785.
- [2] BOLTHAUSEN, E. An iterative construction of solutions of the tap equations for the sherrington–kirkpatrick model. *Communications in Mathematical Physics* 325, 1 (2014), 333–366.
- [3] CHATTERJEE, S. A simple invariance theorem. *arXiv preprint math/0508213* (2005).
- [4] FENG, O. Y., VENKATARAMANAN, R., RUSH, C., AND SAMWORTH, R. J. A unifying tutorial on approximate message passing. *Foundations and Trends in Machine Learning* 15, 4 (2022), 335–536.
- [5] FOX, C. W., AND ROBERTS, S. J. A tutorial on variational bayesian inference. *Artificial intelligence review* 38 (2012), 85–95.
- [6] GUERRA, F., AND TONINELLI, F. L. The thermodynamic limit in mean field spin glass models. *Communications in Mathematical Physics* 230 (2002), 71–79.
- [7] MONTANARI, A., AND SEN, S. A short tutorial on mean-field spin glass techniques for non-physicists. *arXiv preprint arXiv:2204.02909* (2022).
- [8] PANCHENKO, D. *The sherrington-kirkpatrick model*. Springer Science & Business Media, 2013.
- [9] PERRY, A., WEIN, A. S., BANDEIRA, A. S., AND MOITRA, A. Optimality and sub-optimality of pca for spiked random matrices and synchronization. *arXiv preprint arXiv:1609.05573* (2016).
- [10] TALAGRAND, M. The generalized parisi formula. *Comptes Rendus Mathematique* 337, 2 (2003), 111–114.